Fast, stable and accurate approximations with Fourier extensions

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Outline of the talk

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Fourier series

Let $f : [-1,1] \rightarrow \mathbb{R}$. Its N^{th} partial Fourier series is

$$f_N(x) = \sum_{|n| \le N} \hat{f}_n \mathrm{e}^{\mathrm{i} n \pi x}, \qquad N \in \mathbb{N},$$

where

$$\hat{f}_n = rac{1}{2} \int_{-1}^1 f(x) \mathrm{e}^{-\mathrm{i} n \pi x} \, \mathrm{d} x, \quad n \in \mathbb{Z},$$

are the Fourier coefficients of f.

Fourier series are extremely effective tools in computations.

Reason 1: rapid convergence of Fourier series

The Fourier series f_N converges geometrically fast whenever f is analytic and periodic, i.e.

$$||f - f_N||_{\infty} := \sup_{x \in [-1,1]} |f(x) - f_N(x)| \sim \rho^{-N},$$

for some $\rho > 1$.



2. Computations can be carried out rapidly, in $\mathcal{O}(N \log N)$ time, with the FFT.

3. Fourier series lead to stable numerical algorithms (spectral methods) for PDEs.

Reason 4: resolution power of Fourier series

Fourier series are good at resolving periodic oscillations.

• Obtain the optimal resolution constant of 2 d.o.f. per wavelength.



Graphs of $f(x) = \cos 20\pi x + \exp(\sin 2\pi x)$ (blue) and $f_N(x)$ (red).

Conversely, expansions in orthogonal polynomials (e.g. Chebyshev polynomials) have a higher resolution constant equal to π .

Limitations of Fourier series I

Most functions are **not** periodic.

The Fourier series of a nonperiodic function gives a very poor approximation.

- Gibbs phenomenon.
- ► No uniform convergence.





Limitations of Fourier series II

Fourier series are limited to simple geometries.

• E.g. intervals, (hyper)rectangles, parallelopipeds.



Some extensions to certain triangles and simplices. But require rather unphysical notions of periodicity. Is there a way to retain the good properties of Fourier series of periodic functions, i.e.

- (i) rapid convergence,
- (ii) good resolution power,
- (iii) easy manipulation via the FFT,

for nonperiodic functions, and functions defined in arbitrary domains?

Answer

Yes! One can compute approximations of analytic, nonperiodic functions which

- (i) are expressed in terms of a Fourier series,
- (ii) converge rapidly,
- (iii) have a resolution constant that can be made arbitrarily close to 2 by an appropriate choice of a certain parameter,
- (iv) are numerically stable,
- (v) in 1D at least, can be computed efficiently.

The method is based on so-called Fourier extensions.

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An (old) idea

Seek to approximate a function $f : \Omega \to \mathbb{R}$ by a Fourier series on a larger, (hyper)rectangular domain.



Known as the Fourier extension problem.

The Fourier extension problem

Existence/construction of extensions:

- ▶ Whitney (1934), Hestenes (1941), Fefferman (2005),...
- However, typically cannot obtain geometric convergence this way no analytic and periodic extension of an arbitrary analytic function.
- Throughout, we shall never explicitly calculate extensions.

Computation of extensions:

- Boyd (2002), Bruno (2003), Bruno et al (2007), Huybrechs (2010), BA & Huybrechs (2011), BA et al (2012).
- SVD's, fast computations, smoothing of extensions: Lyon (2011, 2012).

Applications of extensions:

Solution of PDEs in complex geometries, Lyon & Bruno (2010, 2011), Albin & Bruno (2011).

One-dimensional Fourier extensions



We seek an approximation $f_N \in \mathcal{G}_N$, where

$$\mathcal{G}_{N} = \operatorname{span}\left\{\frac{1}{\sqrt{2T}}\mathrm{e}^{\mathrm{i}\frac{n\pi}{T}x}: n = -N, \dots, N\right\},$$

is the set of Fourier series of degree N on [-T, T], and T > 1 is fixed (up to the user).

Question: how should we compute f_N ?

Least squares

Define

$$f_{N} := \underset{\phi \in \mathcal{G}_{N}}{\operatorname{argmin}} \|f - \phi\|,$$

where $||g||^2 = \int_{-1}^1 |g(x)|^2 \, \mathrm{d}x$.

- Results in a linear system for the coefficients of $F_N(f)$.
- We refer to $F_N(f)$ as the continuous Fourier extension of f.

Problem: we need to know the integrals $\int_{-1}^{1} f(x) e^{-i\frac{n\pi}{T}x} dx$.

Discrete least squares

Intstead, we can replace integrals by a quadrature, leading to

$$f_N := \operatorname*{argmin}_{\phi \in \mathcal{G}_N} \sum_{|n| \le N} |f(x_n) - \phi(x_n)|^2.$$

• We refer to $\tilde{F}_N(f)$ as the discrete Fourier extension of f.

Question: what are good nodes to choose?

Fourier extensions as polynomial approximations

The set \mathcal{G}_N consists of the functions

$$\cos \frac{k\pi}{T}x$$
, $\sin \frac{(k+1)\pi}{T}x$, $k = 0, \dots, N$.

If $c(T) = \cos \frac{\pi}{T}$ and

$$y = y(x) := \cos \frac{\pi}{T} x, \qquad y : [0,1] \rightarrow [c(T),1],$$

then

$$\cos \frac{k\pi}{T} x \in \mathbb{P}_k, \qquad \sin \frac{(k+1)\pi}{T} x / \sin \frac{\pi}{T} x \in \mathbb{P}_k.$$

Thus, any FE can be written as a sum of two polynomials expansions of degree N in the variable y, corresponding to the even and odd parts of f respectively.

Choice of nodes

Optimal nodes for polynomial interpolation in $z \in [-1,1]$ are the Chebyshev nodes

$$z_n = \cos\left(\frac{(2n+1)\pi}{2N+2}\right), \quad n=0,\ldots,N.$$

Mapping back to the *x*-domain, we get

$$x_n = \frac{T}{\pi} \cos^{-1} \left\{ \frac{1}{2} (1 - c(T)) \cos \left[\frac{(2n+1)\pi}{2N+2} \right] + \frac{1}{2} (1 + c(T)) \right\},\$$

for $n = 0, \ldots, N$, and $x_{-n} = -x_n$ otherwise.

• We refer to these as mapped symmetric Chebyshev nodes.

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Convergence

The expansion of an analytic function g in (almost) any orthogonal polynomial system converges geometrically fast at rate ρ , where ρ is the index of the largest Bernstein ellipse

$$\mathcal{B}(\rho) = \left\{ \frac{1}{2} \left(\rho \mathrm{e}^{\mathrm{i}\theta} + \rho^{-1} \mathrm{e}^{-\mathrm{i}\theta} \right) : \theta \in [-\pi, \pi) \right\}, \quad \rho \ge 1,$$

within which g is analytic.



Convergence

Let $\mathcal{D}(\rho)$ be the image of $\mathcal{B}(\rho)$ in the x-domain, and set

$$E(T) = \cot^2\left(\frac{\pi}{4T}\right).$$

Theorem (Huybrechs (2010), BA & Huybrechs (2011)) Suppose that f is analytic in $\mathcal{D}(\rho^*)$ and continuous on its boundary. Then

$$\|f-f_N\|_{\infty}\leq c_f\rho^{-N},$$

where $\rho = \min \{\rho^*, E(T)\}$ and $c_f > 0$ is proportional to $\max_{x \in \mathcal{D}(\rho)} |f(x)|$.

The map y = cos π/T x introduces a square-root type singularity in the complex plane. This limits the maximal ρ to E(T).

Numerical example

Let $T = \frac{4}{3}, \frac{3}{2}, 2, 4$:



The error $||f - f_N||_{\infty}$ for $f(x) = e^{5x}$

Note that E(T) is an increasing function of T, with E(1) = 1.

Resolution power

By analyzing the behaviour of the Fourier extension of

$$f(x)=\mathrm{e}^{\mathrm{i}\pi\omega x},\quad x\in[-1,1],$$

for large $\omega \gg 1$, one can show:

Theorem (BA & Huybrechs (2011)) The number of points-per-wavelength r(T) required to resolve the function $f(x) = e^{i\pi\omega x}$ satisfies

$$r(T) \leq 2T \sin\left(rac{\pi}{2T}
ight), \quad T>1.$$

In particular, $r(T) \sim 2 + O(T-1)$ as $T \rightarrow 1$.

• The PPW for standard Fourier series is the limiting value for r(T).

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The error $||f - f_N||_{\infty}$ against *N*, where f_N is the finite (black) or infinite (blue) precision FE with T = 2.

Conclusion

The differences between the infinite- and finite-precision computations suggest that either:

- (i) The theorems are wrong!
- (ii) The code has a bug!
- (iii) The finite-precision solver does not give an extension which is 'close' to the infinite-precision FE.

Fortunately for my collaborators and me, (iii) is correct.

 \Rightarrow analysis of infinite-precision extensions is of limited use in understanding the results of finite-precision computations.

Ill-conditioning

The discrete FE requires solution of a linear system

Aa = b,

where $A \in \mathbb{C}^{(2N+1)\times(2N+1)}$ and $a \in \mathbb{C}^{2N+1}$ is the vector of coefficients of $\tilde{F}_N(f)$.

Theorem (BA et al. (2012)) The condition number of A satisfies $\kappa(A) = \mathcal{O}\left(E(T)^N\right), \quad N \to \infty.$

Moreover, the numerical rank of A is roughly 2N/T for large N.

Explanation: Any function f defined on [-1, 1] has infinitely many extensions to [-T, T]. Redundancy \Rightarrow numerical ill-conditioning.

Intuitive argument

1. For large N, the matrix A is highly underdetermined.

2. The numerical solver (e.g. *Matlab's* backslash) will use these degrees of freedom to seek coefficient vectors \tilde{a} satisfying

 $A\tilde{a}\approx b, \qquad \|\tilde{a}\|\ll\infty.$

3. One can show that, if $f \in \mathcal{D}(\rho)$, then

 $\|a\|\approx (E(T)/\rho)^N.$

4. Hence, ||a|| is exponentially large in N for $\rho < E(T)$, and we must therefore have

 $\tilde{a} \neq a$, *N* large.

Numerical example



Top row: the error $||f - f_N||_{\infty}$ against *N*, where f_N is the finite (black) or infinite (blue) precision FE. Bottom row: the norms $||\tilde{a}||$ (black) and ||a|| (blue) against *N*.

Existence of small-norm approximate coefficients



Lemma

Let $f \in H^{k}(-1,1)$, $k \in \mathbb{N}$. Then there exists $\tilde{a} \in \mathbb{C}^{2N+1}$ satisfying (i) $\|\tilde{a}\| \lesssim \|f\|_{H^{k}}$ (small norm), (ii) $\|A\tilde{a} - b\| \lesssim N^{-k} \|f\|_{H^{k}}$ (approximate solution), (iii) $\|f - \sum_{|n| \le N} a_{n}\phi_{n}\| \lesssim N^{-k} \|f\|_{H^{k}}$ (good approximation of f).

Conclusion: In finite-precision, geometric convergence may be sacrificed for superalgebraic convergence for all large N.

Analysis of the finite-precision FE

Assumption 1. The result of the numerical solver is similar to that of a truncated SVD.

Assumption 2. Errors in the truncated SVD can be ignored.

Agrees with numerical experiment.

We now consider the approximation $f \approx g_{N,\epsilon}$, where $g_{N,\epsilon}$ is the FE obtained by solving

$$Aa = b,$$

using an SVD with truncation parameter ϵ ..

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Analysis of $G_{N,\epsilon}(f)$

Recall that

$$\mathcal{G}_{N} = \operatorname{span}\left\{\frac{1}{\sqrt{2T}}\mathrm{e}^{\mathrm{i}\frac{n\pi}{T}x}: n = -N, \ldots, N\right\}.$$

Theorem For any $\phi \in \mathcal{G}_N$, we have $\|f - g_{N,\epsilon}\|_{\infty} \lesssim \|f - \phi\|_{\infty} + \epsilon \|\phi\|_{T,\infty},$ (*) where $\|\cdot\|_{T,\infty}$ is the uniform norm on [-T, T].

Phases of convergence

1. Setting
$$\phi = f_N$$
 in (*) gives

$$\|f-g_{N,\epsilon}\|_{\infty} \lesssim c_f \rho^{-N} \left(1+\epsilon E(T)^N\right).$$

The RHS decreases geometrically for

$$N \leq N_1 := -rac{\log E(T)}{\log \epsilon},$$

and increases geometrically for $N > N_1$.

2. However, recall that there exist functions ϕ with small norm coefficient vectors. When substituted into (*) these give

$$\|f-g_{N,\epsilon}\|_{\infty} \lesssim \|f\|_{\mathrm{H}^{k}}\left(N^{-k}+\epsilon\right).$$

Summary

- 1. $N \leq N_1$. Geometric convergence in N.
- 2. $N = N_1$. The error satisfies

$$\|f - g_{N,\epsilon}\|_{\infty} \lesssim c_f \epsilon^{d_f}, \quad d_f = \frac{\log \rho}{\log E(T)} \in (0,1].$$

3. $N > N_1$. Superalgebraic convergence down to a maximal accuracy of order ϵ .

Remarks:

- ▶ If f is sufficiently analytic, then $d_f = 1$. If c_f is also small, then convergence stops at $N = N_1$. Otherwise, there is a further regime of superalgebraic convergence.
- The breakpoint is function-independent. Up to constant factors, it is the largest N for which all singular values of A are greater than ε.

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Numerical Example



Top row: the error $||f - f_N||_{\infty}$ against *N*, where f_N is the finite (black) or infinite (blue) precision FE. Bottom row: the norms $||\tilde{a}||$ (black) and ||a|| (blue) against *N*.

One can prove that the condition number of the numerical mapping $f \mapsto f_N$ satisfies $\kappa_N = \mathcal{O}(1)$ for all N.

40	80	120	160	200
$1.44 imes10^{0}$	$1.45 imes10^{0}$	$1.41 imes10^{0}$	$1.46 imes10^{0}$	$1.42 imes 10^{0}$

The condition number κ_N for T = 2

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Background

In many problems one has only samples of f at equispaced points:

$$f(\frac{n}{M}), |n| \leq M.$$

Equispaced data is difficult to handle.

Runge phenomenon: the polynomial interpolant of f at equispaced nodes diverges unless f is analytic in a sufficiently large region.



Graphs of $f(x) = \frac{1}{1+20x^2}$ (black) and its equispaced polynomial interpolant (blue).

A result of Platte, Trefethen & Kuijlaars (PTK)

Problem: given $\{f(\frac{n}{M})\}_{|n| \le M}$, recover f to high accuracy.

Many methods have been proposed to do this. However,

Theorem (Platte, Trefethen & Kuijlaars (2011))

"Any method that recovers analytic functions f to exponential accuracy using only the grid values $\{f(\frac{n}{M})\}_{|n| \leq M}$ must be exponentially ill-conditioned. The best possible convergence for a stable method is root-exponential in M."

Fourier extensions for equispaced data

We define

$$f_{N,M} := \operatorname*{argmin}_{\phi \in \mathcal{G}_N} \sum_{|n| \leq M} |f(\frac{n}{M}) - \phi(\frac{n}{M})|^2.$$

Questions:

- (i) How large does M need to be, for a given N?
- (ii) What is the corresponding convergence rate and condition number, and how does this relate to Platte, Trefethen & Kuijlaars (PTK)?
- (iii) Are the results for (i) and (ii) different in finite and infinite precision?

The infinite-precision FE

It is possible to show the following:

- 1. If $M = \gamma N$ for $\gamma \ge 1$ fixed, then
 - (i) The condition number $\kappa_{N,\gamma N}$ is exponentially large in N,
- (ii) The Fourier extension $f_{N,\gamma N}$ diverges exponentially fast for any analytic function having a singularity in a certain complex region \mathcal{R}_{γ} containing [-1, 1].
- 2. One requires the scaling $M = O(N^2)$ to avoid (i) and (ii).

3. If $M = \mathcal{O}(N^2)$, then $f_{N,M}$ converges geometrically fast in N at the same rate as the discrete FE, and the condition number $\kappa_{N,M}$ is bounded.

 \Rightarrow In infinite precision, FE's attain the stability barrier of PTK.

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Example

Infinite precision:



The error $||f - f_{N,M}||_{\infty}$ against M for $f(x) = \frac{1}{1+100x^2}$, where N = M (black), N = 2/3M (blue) and $N = 2\sqrt{M}$ (red)

Divergence for $M = \mathcal{O}(N)$.

Example

Finite precision:



The error $||f - f_{N,M}||_{\infty}$ against M for $f(x) = \frac{1}{1+100x^2}$, where N = M (black), N = 2/3M (blue) and $N = 2\sqrt{M}$ (red)

Convergence with $M = \mathcal{O}(N)$. The scaling $M = \mathcal{O}(N^2)$ is unnecessary.

The finite-precision FE

By analysing the truncated SVD FE, one can show the following:

1. The condition number

$$\kappa_{N,\gamma N} \lesssim \epsilon^{-a(\gamma;T)},$$

where $a(\gamma; T)$ is independent of N and satisfies

•

 \Rightarrow the condition number can be made arbitrarily close to 1 for all N by a suitable choice of $\gamma.$

The finite-precision FE

2. The error satisfies

$$\|f - f_{N,\gamma N}\|_{\infty} \lesssim \epsilon^{-a(\gamma;T)} \left(\|f - \phi\|_{\infty} + \epsilon \|\phi\|_{T,\infty}\right), \quad \forall \phi \in \mathcal{G}_N.$$

Hence

(i) N ≤ N₁. Geometric convergence in N.
(ii) N = N₁. The error satisfies

$$\|f - f_{N_1,\gamma N_1}\|_{\infty} \lesssim c_f \epsilon^{d_f - a(\gamma;T)}, \quad d_f = \frac{\log \rho}{\log E(T)}.$$

(iii) N > N₁. Superalgebraic convergence down to a maximal accuracy of order ε^{1-a(γ; T)}.

The stability barrier can be circumvented to a substantial extent. With FE's, we have:

- (i) Bounded condition numbers,
- (ii) Rapid convergence, but only down to a finite tolerance.

 \Rightarrow No contradiction with PTK.

Examples



The error $||f - f_{M/\gamma,M}||_{\infty}$ against *M*, where T = 2 and $\gamma = 1$ (black), $\gamma = \frac{3}{2}$ (blue) or $\gamma = 2$ (red).

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Two parameters:

- T the extension domain size,
- γ the amount of oversampling.

Question: How do we best choose T and γ ?

 For obvious reasons, we are most interested in function independent choices.

Factors

	stability	maximal accuracy	convergence
small γ	worse	worse	better
large γ	better	better	worse

	stability	maximal accuracy	convergence
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Experiment

Fix *T*. For each *M*, find the largest value of *N* such that the condition number $\kappa_{N,M} \leq \kappa_0$, where κ_0 is some prescribed value. This gives a function

 $\Theta(M; T) = \max \{ N : \kappa_{N,M} \le \kappa_0 \}, \quad M \in \mathbb{N}.$



The function $\Theta(M; T)/M$ against M, where T = 4, 3, 2, 3/2, 7/6.

Numerical results



$$f(x) = e^{60\sqrt{2\pi}ix}$$
 $f(x) = \frac{1}{1+200x^2}$ $f(x) = \frac{1}{20-19x}$

Top row: f(x). Bottom row: the error $||f - f_{\Theta(M;T),M}||_{\infty}$ against M, where T = 4, 3, 2, 3/2, 7/6.

Numerical results



 $f(x) = \operatorname{Ai}(-30x - 28)$ $f(x) = \sin 100x^2$ $f(x) = e^{\sin(5.4\pi x - 2.7\pi) - \cos(2\pi x)}$

Top row: f(x). Bottom row: the error $||f - f_{\Theta(M;T),M}||_{\infty}$ against M, where T = 4, 3, 2, 3/2, 7/6.

Conclusion

The choice of T makes almost no difference!

Recommendation: choose T = 2

Reason: fast computations in $\mathcal{O}(N(\log N)^2)$ time, Lyon (2012)

Conclusions and open problems

Despite severely ill-conditioned matrices, one can compute numerically stable, rapidly convergent Fourier extensions of arbitrary functions, even when only equispaced data is prescribed.

Challenges

- Higher dimensions: simplicial domains (triangles, tetrahedra,...)
- Higher dimensions: arbitrary domains
- \blacktriangleright Explaining the apparent γ and ${\cal T}$ independence
- Other data (nonuniform, Fourier, etc)

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